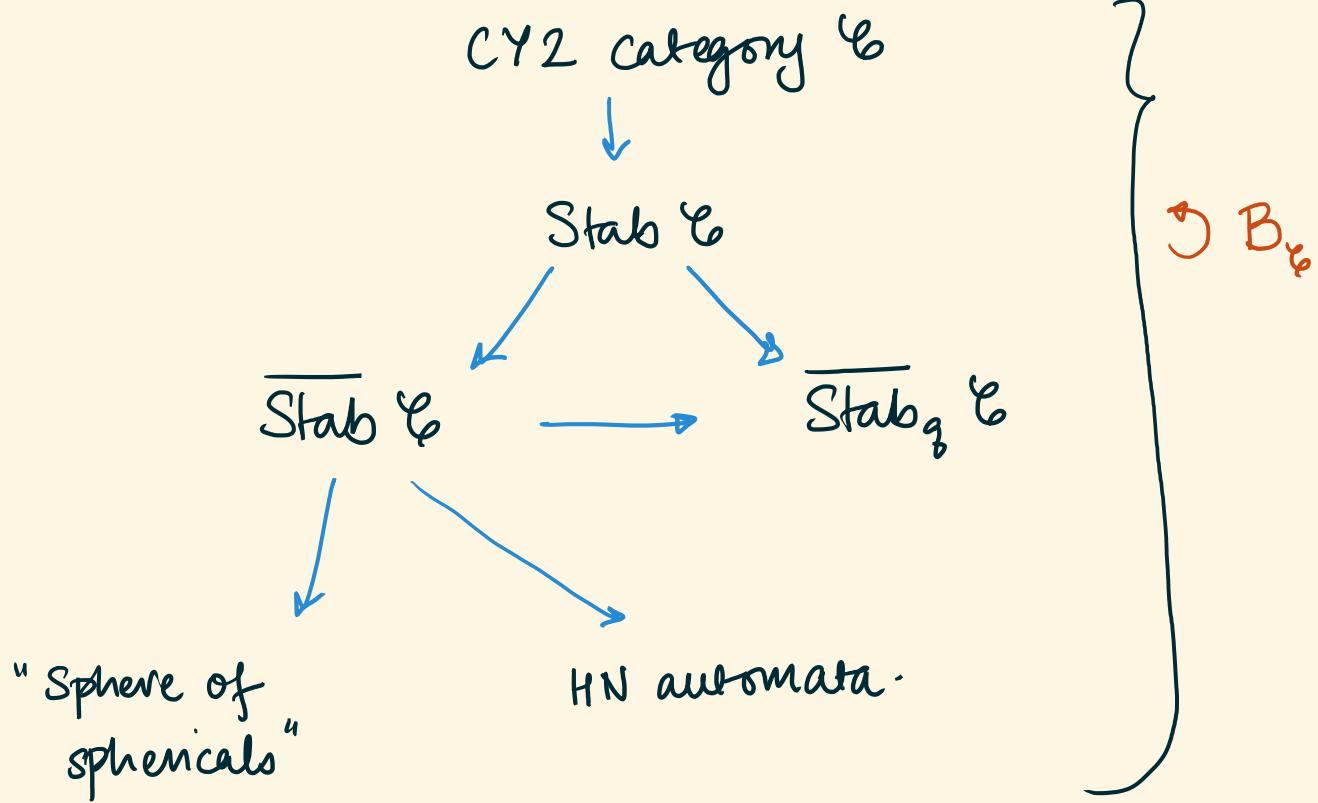


# A Thurston compactification for stability space

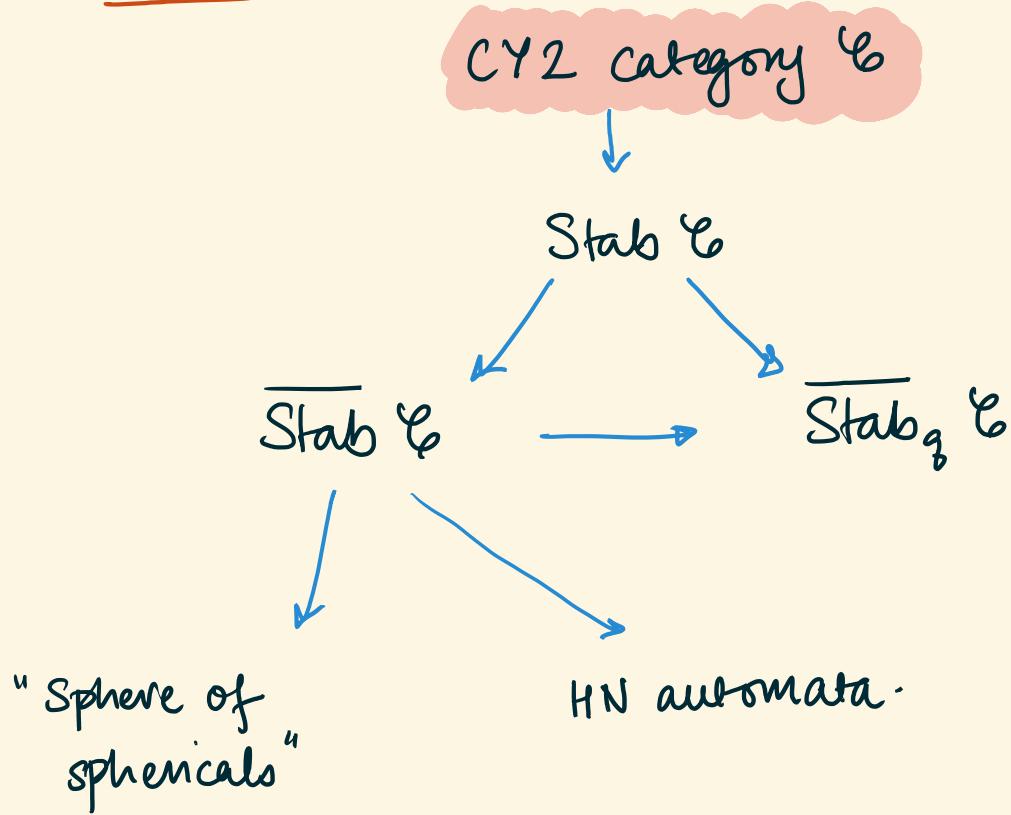
References:

- 1) B - Deshpurkar - Licata
- 2) Louis Becker honours thesis

# Plan



# Plan



## Our category

• — ! — •

Γ a connected graph

$\mathcal{C}_\Gamma$  triangulated category generated  
by  $\{P_i \mid i \in \Gamma\}$ .

## Our category



$\Gamma$  a connected graph

$\mathcal{C}_\Gamma$  triangulated category generated  
by  $\{P_i \mid i \in \Gamma\}$ .

$n \rightarrow$	0	1	2
$hom^n(P_i, P_i)$	1	0	1
$hom^n(P_i, P_j)$	0	1	0

if

## Facts

1)  $\mathcal{C}_\Gamma$  is CY 2 :  $\text{Hom}(x, y) \cong \text{Hom}(y, x[2])^\vee$

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a bounded t-structure on  $\mathcal{C}_\Gamma$
- "standard heart"
- \* We'll focus on  $\Gamma = A_n$  .—.—.—.

### Example

$$\Gamma = A_2 \quad \bullet \text{---} \bullet$$

$\mathcal{C}_\Gamma$  has  $P_1$  &  $P_2$  with

$$\hom^1(P_1, P_2) = \hom^1(P_2, P_1) = 1$$

$\Rightarrow \exists!$  non-split exact triangle

$$P_2 \rightarrow * \rightarrow P_1 \rightarrow P_2[1]$$

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call this " $P_1 \rightarrow P_2$ "

Similarly, we have " $P_2 \rightarrow P_1$ "

## Spherical twists

Let  $X \in \mathcal{C}_\Gamma$  be a spherical object.

We have a functor, the spherical twist in  $X$  [Seidel-Thomas] :

$$\sigma_X : \mathcal{C}_\Gamma \rightarrow \mathcal{C}_\Gamma \quad \text{with}$$

$$\sigma_X = \text{Cone}(\text{Hom}(X, Y) \otimes X \xrightarrow{\text{ev}} Y)$$

## Facts

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- 2)  $\{\sigma_{P_i}\}$  satisfy braid relations  
 $\Rightarrow$  braid group of  $\Gamma$  acts on  $\mathcal{C}_\Gamma$

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- 2)  $\{\sigma_{P_i}\}$  satisfy braid relations
- 3) If  $Y$  spherical, then  $\sigma_X(Y)$  spherical
- 4) If  $\Gamma$  is type ADE then all sphericals  
are in one orbit under the spherical  
twist group.

Example :   •—•       $\Gamma = A_2$

$$\sigma_{P_1}(P_1) = P_1[-1] \quad \sigma_{P_2}(P_1) = P_2 \rightarrow P_1$$

$$\sigma_{P_1}(P_2) = P_1 \rightarrow P_2 \quad \sigma_{P_2}(P_2) = P_2[-1]$$

$\Rightarrow P_1 \rightarrow P_2, P_2 \rightarrow P_1$  are spherical.

Example :  $\bullet \longrightarrow \bullet \quad \Gamma = A_2$

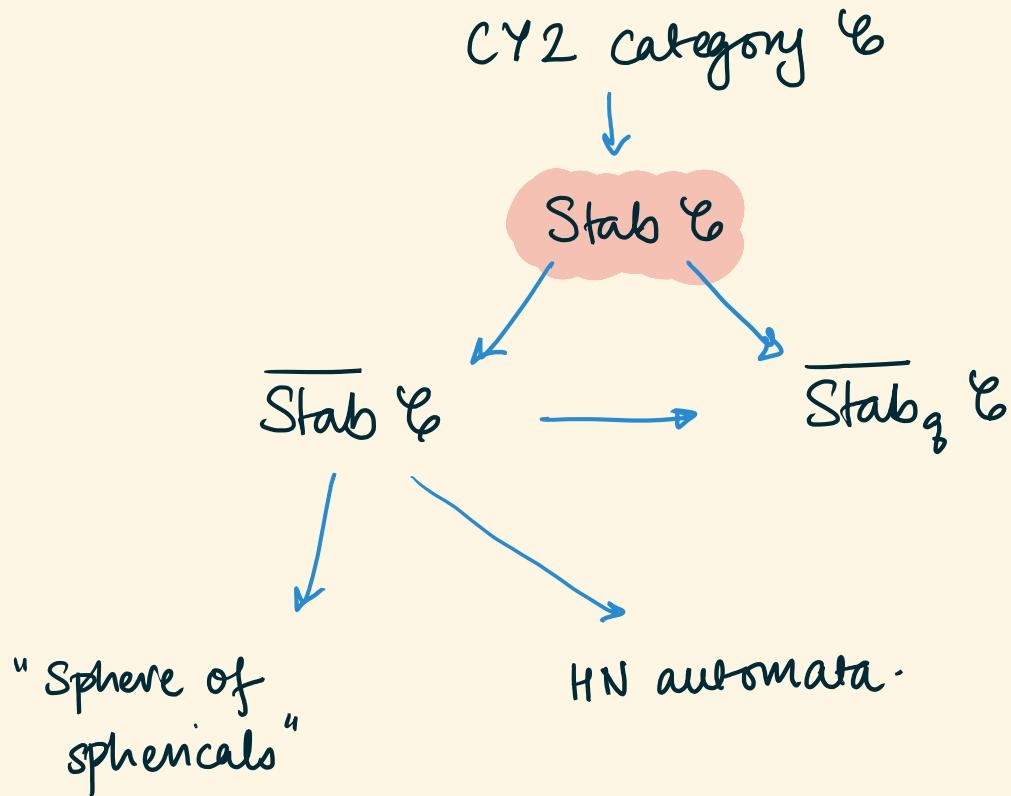
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Theme in the remainder of the talk:

understand  $\text{Stab}_{\mathcal{C}_\Gamma}^+$  via the spherical objects & twist group action on them

# Plan



## Stability conditions & stability space

A stability condition on  $\mathcal{C}_r$  consists of  
a compatible pair

$$Z : \text{---} \begin{array}{c} \nearrow \\ \searrow \end{array} \quad \text{and} \quad P : \text{=====} \textcolor{red}{|||||}$$

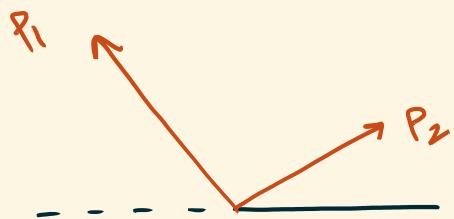
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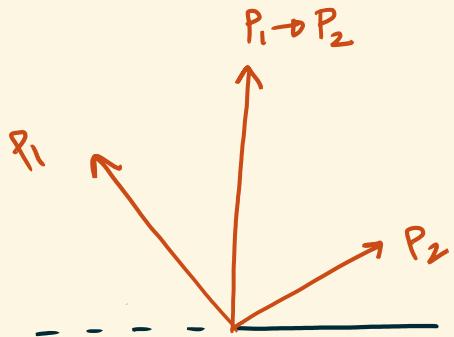


Set  $\text{Stab } \mathcal{C}_\Gamma$  to be the space of  $(Z, P)$   
modulo natural  $\mathbb{C}$ -action

Example :  $T = A_2$      • — •

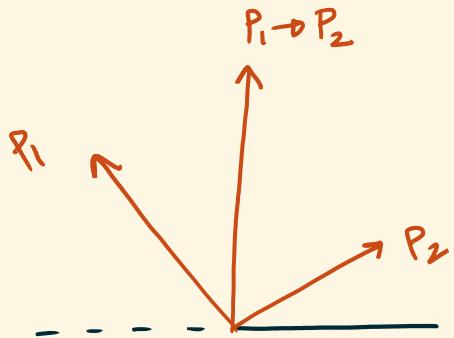


Example :  $T = A_2$       • — •



These are the stable objects (up to shift)

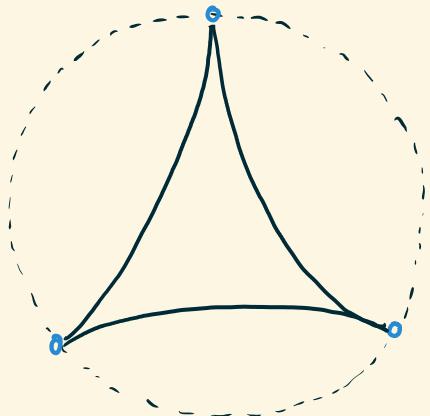
Example :  $T = A_2$       •—•



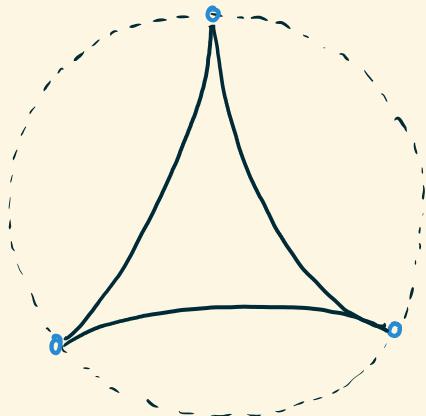
These are the stable objects (up to shift)

\*  $T \in \text{Stab}$  determined uniquely by  
three sides of a  $\Delta$ .

Stab  $\mathcal{C}_{A_2}$



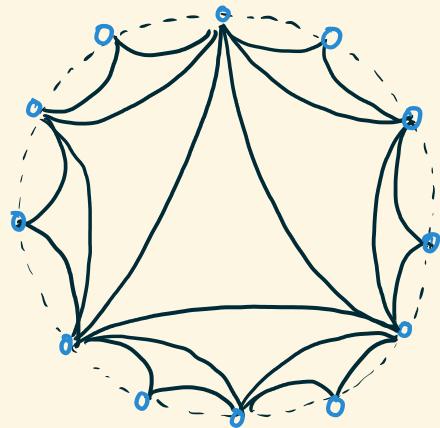
Stab  $\mathcal{C}_{A_2}$



Theorem [Thomas, Bridgeland-Qiu-Sutherland]

$\text{Stab } \mathcal{C}_{A_2} \cong \text{open disk}$

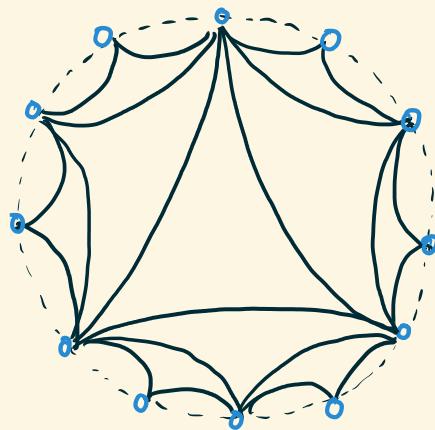
## Stab $\mathcal{C}_{A_2}$



Theorem [Thomas, Bridgeland-Qiu-Sutherland]

$\text{Stab } \mathcal{C}_{A_2} \cong$  open disk, tiled by  
images of  under braid  
group action (via  $\text{PSL}_2(\mathbb{Z})$ ).

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Q : How to fill in the boundary?

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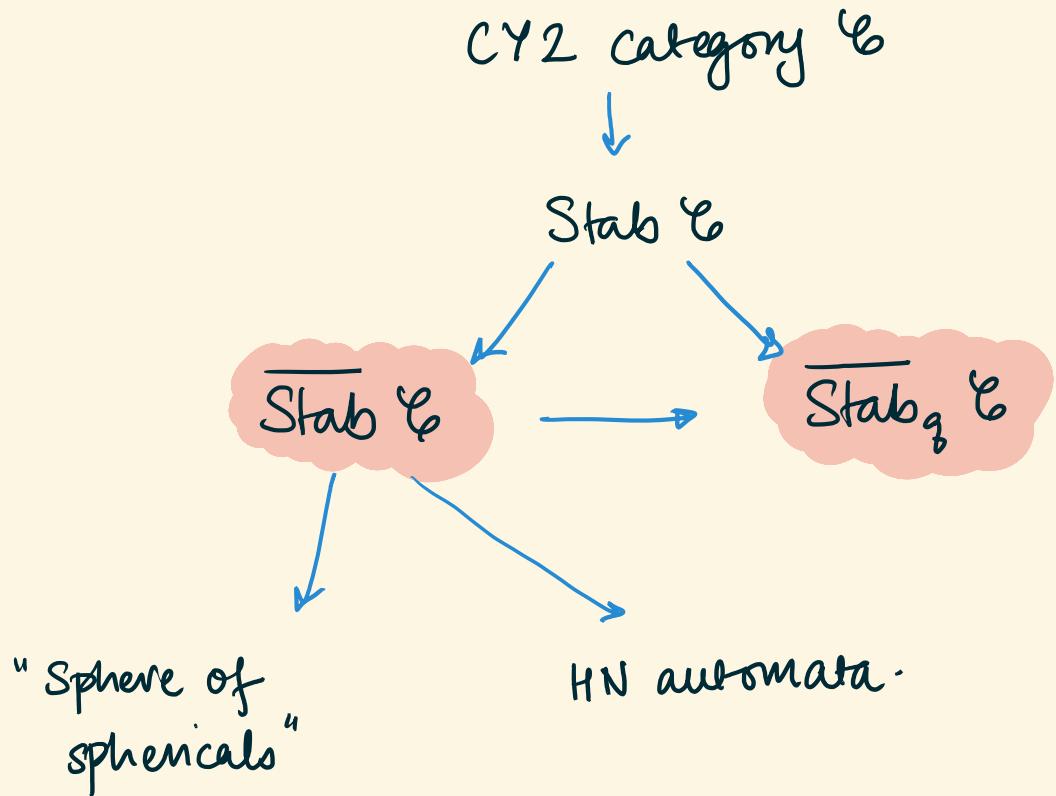
- Intrinsic approach : degenerations of stability conditions (see Bolognese for partial answer)
- Extrinsic approach (following Thurston) :

Embed

$$\text{Stab } \mathcal{C}_r \hookrightarrow \overset{\infty}{\mathbb{P}},$$

then take closure & interpret boundary.

# Plan



## HN filtrations + HN mass

Let  $\mathcal{T}$  be a stability condition.

$$m_{\mathcal{T}}(x) := \begin{cases} |Z(x)| & \text{if } x \text{ } \mathcal{T}\text{-semistable} \\ \sum m_{\mathcal{T}}(x_i) & \text{if } \{x_i\} \text{ the HN} \\ & \text{factors of } x. \end{cases}$$

## HN filtrations + HN mass

Let  $\tau$  be a stability condition.

Fix  $g > 0$ .

$$m_{\tau, g}(x) := \begin{cases} q_D^{\phi(x)} |Z(x)| & \text{if } x \text{ } \tau\text{-semistable} \\ \sum m_{\tau, g}(x_i) & \text{if } \{x_i\} \text{ the HN} \\ & \text{factors of } x. \end{cases}$$

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\*  $m_{\mathcal{T}, g}(x)$  "measures"  $x$  with respect to  $\mathcal{T}$ .

$$q_b=1 \quad q_b>0$$

Theorem [BDL, Becker]

Let  $T$  be connected.

Then  $T \in \text{Stab } G$  can be recovered from

$$\langle m_{T,q_b}(x) \mid x \text{ spherical} \rangle$$

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Let  $S = \text{sphericals of } \mathcal{C}_T$ . Define

$$m_{T,q}: \text{Stab } \mathcal{C}_T \rightarrow \text{PR}^S$$

$$T \mapsto \langle m_{T,q}(x) \mid x \in S \rangle_{\sim}$$

Let  $S$  = sphericals of  $\mathcal{C}_\Gamma$ . Define

$$m_{\tau, q}: \text{Stab } \mathcal{C}_\Gamma \rightarrow \text{PR}^S$$
$$\tau \mapsto \langle m_{\tau, q}(x) \mid x \in S \rangle /_{\sim}$$

Theorem  $\Rightarrow m_{\tau, q}$  is injective.

Set  $\overline{\text{Stab } \mathcal{C}_\Gamma}$  = closure of image.

Boundary points?

Theorem [BDL, Becker] . Let  $x \in S$

$$\left( \lim_{n \rightarrow \infty} m_{\sigma_x^n \tau, q} \right) = \langle \text{hom}(x, y) \mid y \in S \rangle_{\sim}$$

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$$\Rightarrow S \subseteq \overline{\text{Stab } \mathcal{C}_r}$$

$$x \mapsto \langle \hom(x, y) \mid y \in S \rangle_{\sim}$$

## Some conjectures

[ $q=1$ ]

- $\overline{\text{Stab } \mathcal{C}_\Gamma}$  = closed manifold w/ boundary
- $\overline{\text{Stab } \mathcal{C}_\Gamma} \simeq$  closed ball
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→ proved for  $\Gamma = A_2, \hat{A}_1$  [BDL]

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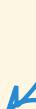
+ a thickened version of  $S$  is dense in the boundary sphere.

# Plan

CY2 category  $\mathcal{C}$



$\text{Stab } \mathcal{C}$



$\overline{\text{Stab}}_g \mathcal{C}$



$\overline{\text{Stab}} \mathcal{C}$



HN automata

"Sphere of  
sphericals"

## HN dynamics of boundary sphericals

- \* Consider  $\Gamma = A_n$  &  $g = 1$ . Fix some  $T$ .

HN supports of sphericals + behaviour under spherical twists is well-behaved.

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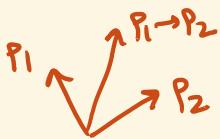
HN supports of sphericals + behaviour under spherical twists is well-behaved.

$\{\Sigma \mid \Sigma = \text{HN support of some spherical}\}$

is constrained.

$\{\Sigma' \mid \Sigma' = \text{HN support of some spherical}\}$

is constrained.

Example : 

$$\Sigma = \{P_2, P_1\}, \{P_1, P_1 \rightarrow P_2\}, \{P_1 \rightarrow P_2, P_2\}$$

& subsets.

## Facts [in progress!]

- 1) A spherical object can be uniquely reconstructed from its HN support & multiplicities

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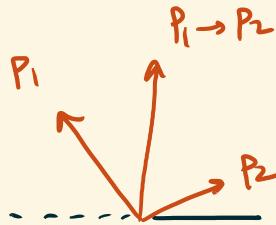
$\dagger$  expect to realise this as  $\mathcal{D}\overline{\text{Stab}}_{C_r}$

## Facts [in progress!]

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- 2) Construct a simplicial complex w/ simplices the possible  $\Sigma$ . Its geometric realisation is a sphere in which the spheres are dense.
- 3) A wall-cross  $\tau \leftrightarrow \tau'$  induces piecewise linear homeomorphisms between these spheres.

Example :

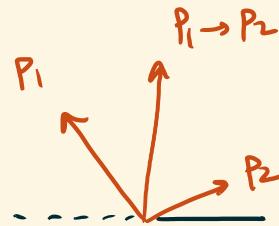
$$\tau = A_2, \tau :$$



Maximal simplices:  $\{P_2, P_1\}$ ,  $\{P_1, P_1 \rightarrow P_2\}$ ,  $\{P_1 \rightarrow P_2, P_2\}$

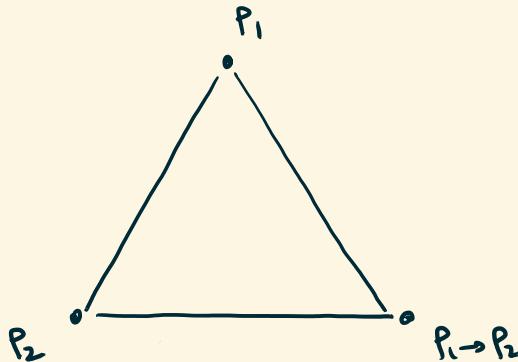
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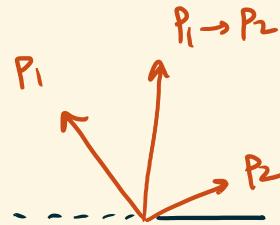
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Geometric realisation:



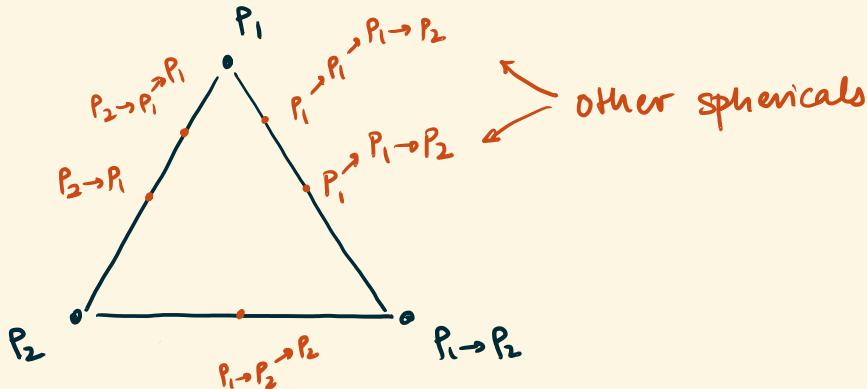
Example :

$$\Gamma = A_2, \quad \tau :$$



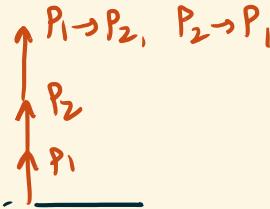
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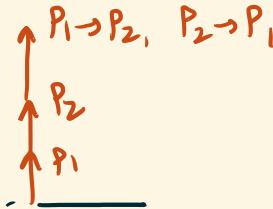
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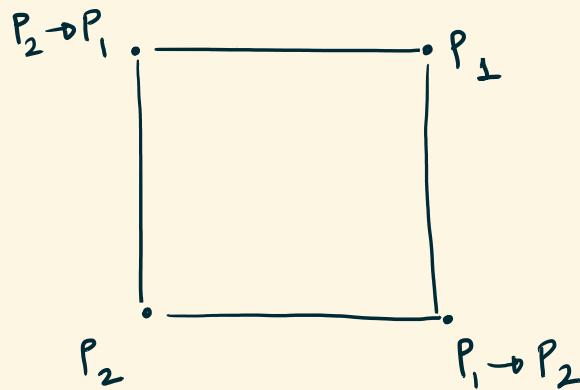
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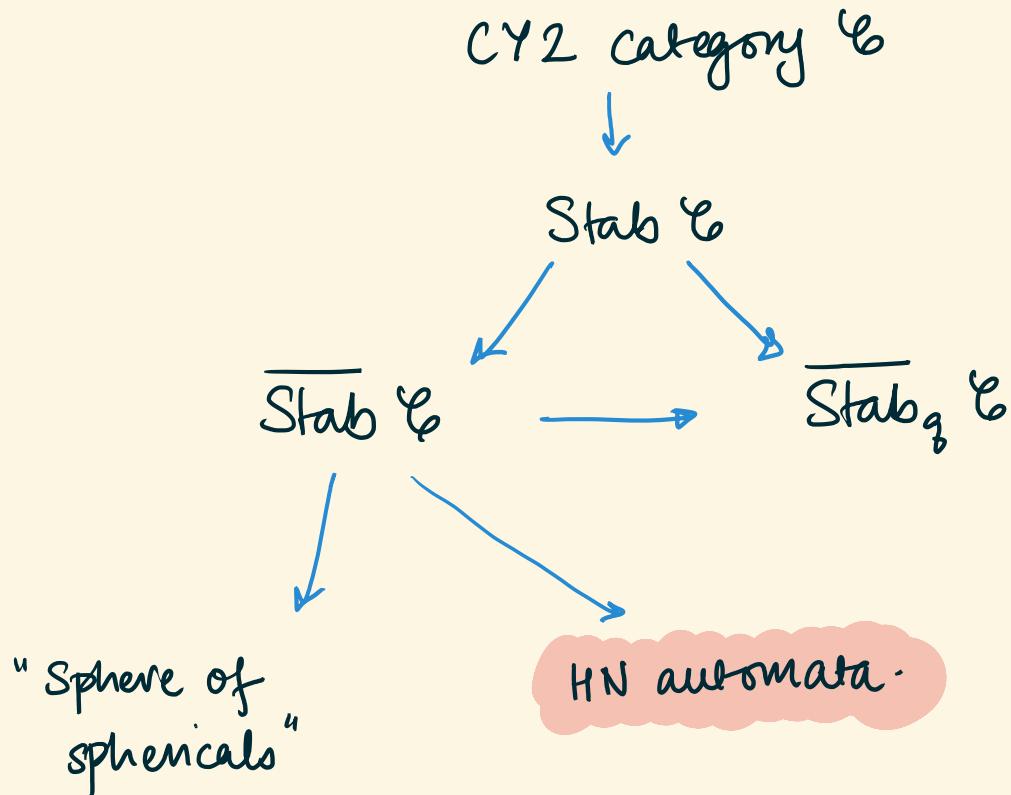


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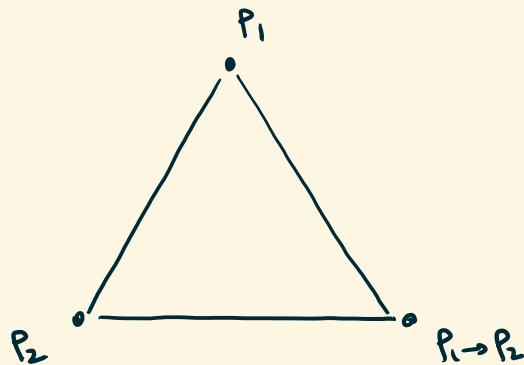


# Plan



## HN automaton (type A<sub>2</sub>)

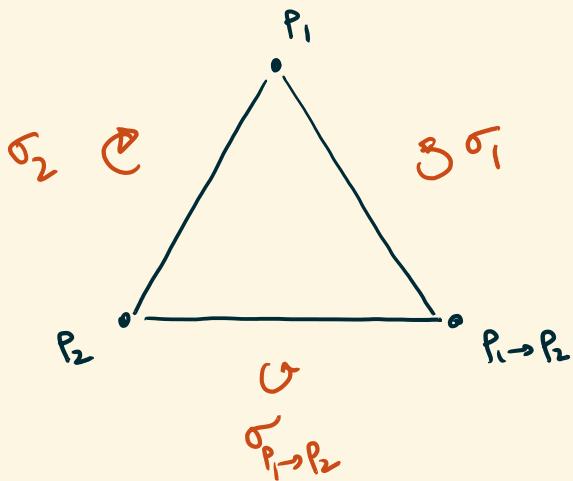
Sometimes, we have more!



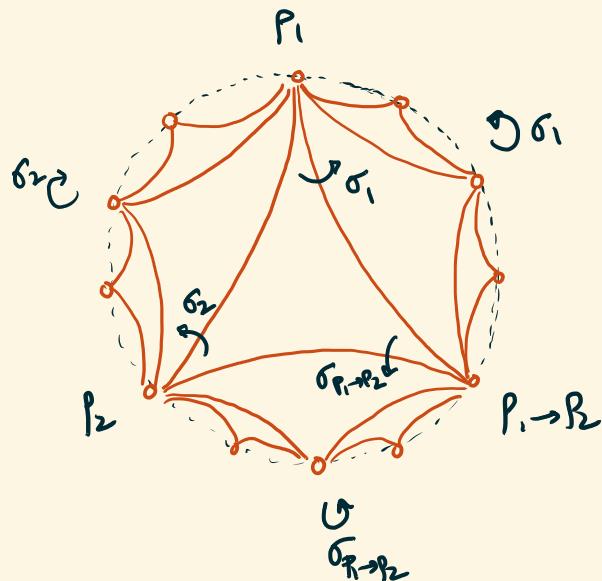
## HN automaton (type A<sub>2</sub>)

Sometimes, we have more! Spherical twists

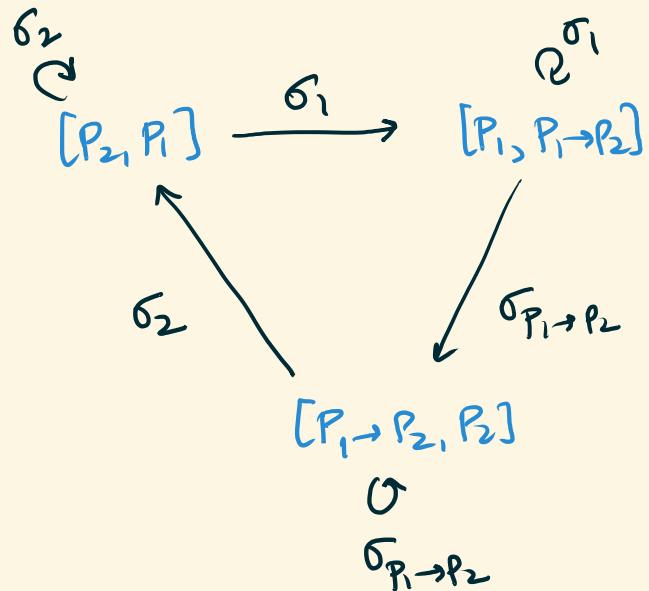
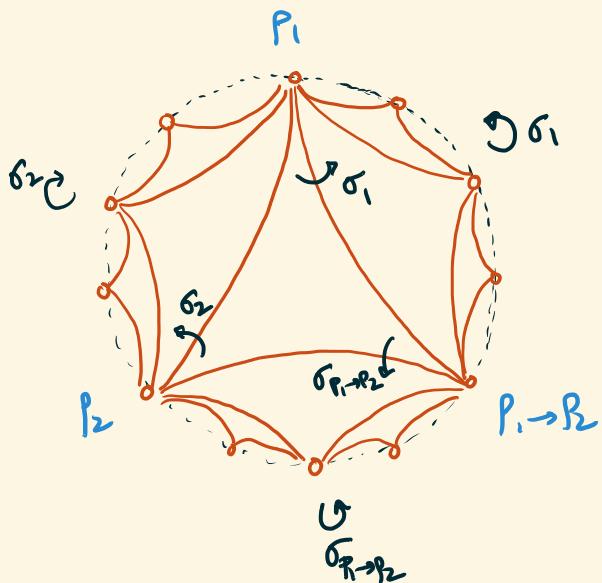
give linear maps  
between simplices that  
control dynamics of  
HN factors.



## HN automaton (type A<sub>2</sub>)



## HN automaton (type A<sub>2</sub>)



## What next?

- A “sphere of sphenicals” for  $A_n$  &  $\hat{A}_n$   
(in progress)
- HN automata for  $A_n, \hat{A}_n$ , more generally
- Understand the remaining points of  $\overline{\text{Stab } \mathcal{C}_r}$   
categorically
- What happens for  $q \neq 1$ ?

Thank you!