

\* Admin: Midterm on 3<sup>rd</sup> Sep, 6:30 pm - 8:30 pm  
Practice problems posted + info document posted.

\* Current topic: The incidence algebra of a poset.  
& its matrix representation.

\* Rule: In this section, we only consider finite posets.

\* Recall: If  $(P, \leq)$  a poset then  $I(P) =$  set of closed intervals.

$\mathcal{A}_P = \{f: I(P) \rightarrow \mathbb{R}\}$  + 3 operations.  
(incidence algebra)

- addition (pointwise)
- scalar multiplication
- multiplication (convolution)

Defn: Let  $f, g \in \mathcal{A}_P$ .

$$(f * g)([x, y]) = \sum_{x \leq z \leq y} f([x, z]) \cdot g([z, y])$$

\* Matrix representation

① Fix a topological sorting of  $P = (p_1, \dots, p_n)$   
such that if  $p_i \leq p_j$  then  $i \leq j$

② For each  $f \in \mathcal{A}_P$ , construct a matrix  $M_f$

$$(M_f)_{(i,j)} = \begin{cases} f([p_i, p_j]) & \text{if } p_i \leq p_j \\ 0 & \text{otherwise.} \end{cases}$$

\* Rule: If  $M$  is any matrix such that  
 $M_{ij} = 0$  whenever  $p_i \not\leq p_j$ , then it comes  
from some  $f \in \mathcal{A}_P$ .

In this case  $f([p_i, p_j]) = M_{ij}$

③ In this case,

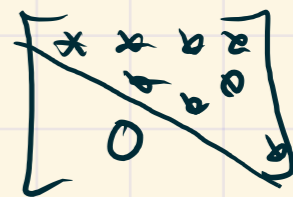
Theorem

$$M_{(f * g)} = M_f \cdot M_g$$

usual matrix product

\* Properties (Assuming a fixed topological sort)

- For any  $f$ ,  $M_f$  is upper-triangular



-  $f_0([x, y]) = 0$  mo

↑

additive identity:

$$f_0 + g = g \text{ for every } g$$

-  $\delta([x, y]) = \begin{cases} 1 & \text{if } x=y \\ 0 & \text{otherwise} \end{cases}$

claim:  $f * \delta = \delta * f = f$

for every  $f$ .

$$(f * \delta)([x, y]) = \sum_{x \leq z \leq y} \underbrace{f([x, z]) \cdot \delta([z, y])}_{\substack{= \\ 0 \\ \text{unless } z=y}}$$

$$= f([x, y]) \delta([y, y])$$

$$= f([x, y])$$

So,  $\delta$  is the multiplicative identity for  $*$ .

$$M_{f_0} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ \vdots & & & \\ 0 & \dots & & 0 \end{bmatrix}$$

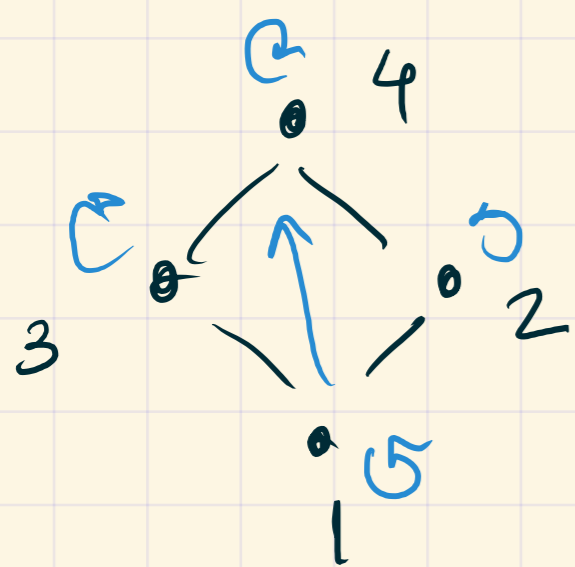
$$M_{f_0} + M = M \text{ for any } M.$$

$$M_\delta = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} = I_n$$

identity matrix.

$$M_\delta \cdot M = M = M \cdot M_\delta \text{ multiplicative identity.}$$

\*  $S([x,y]) = 1$  for every  $x \preceq y$ .



$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$M_Z = \begin{bmatrix} & & & \\ & & & \\ & 0 & & \\ & & & \end{bmatrix}$$

= adjacency matrix.

Q: Invertibility with respect to convolution?

→ we've noted that  $\delta$  is the multiplicative identity.

Defn: Let  $f \in \mathcal{A}_p$ . We say that  $f$  is invertible if there is some  $g \in \mathcal{A}_p$ , such that  $f * g = \delta$ .

Rmk: If such a  $g$  exists, then actually,  $g * f = \delta$  as well.

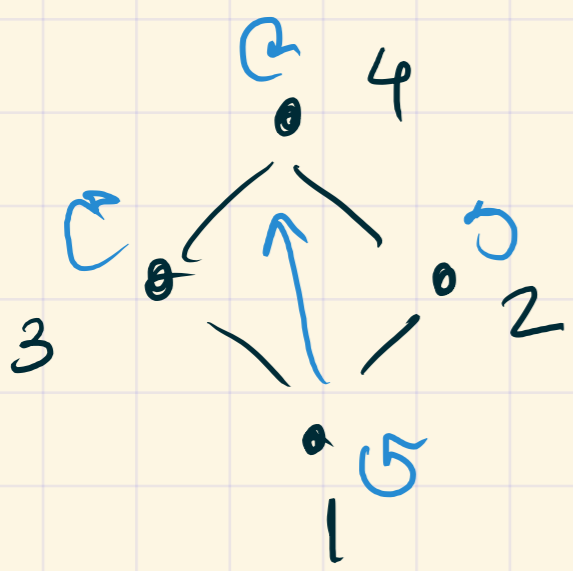
& similarly, if you find a  $g$  such that  $g * f = \delta$ , then automatically

Thm: An upper triangular  $n \times n$  matrix is invertible if and only if every diagonal entry is non-zero. In this case, the inverse is also upper  $\Delta^r$ .

\* Note: Since  $M_Z$  is the adjacency matrix and  $\preceq$  is a (reflexive) partial order relation,  $M_Z$  is an upper  $\Delta$  matrix (by topological sort), and all diagonal entries are 1.

⇒  $M_Z$  always invertible.

↔ this tells us, by going back to functions, that  $Z$  has an inverse under convolution.



$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} = A = M_3$$

Let's try to find the inverse of A.

$$\begin{bmatrix} a & b & c & d \\ 0 & e & f & g \\ 0 & 0 & h & i \\ 0 & 0 & 0 & j \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a & a+b & a+c & a+b+c+d \\ 0 & e & f & e+f+g \\ 0 & 0 & h & h+i \\ 0 & 0 & 0 & j \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

||

$$\begin{bmatrix} 1 & 1+b & 1+c & 1+b+c+d \\ 0 & 1 & f & 1+f+g \\ 0 & 0 & 1 & 1+i \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$1+b=0, f=0, 1+i=0$$

$$b=-1, f=0, i=-1$$

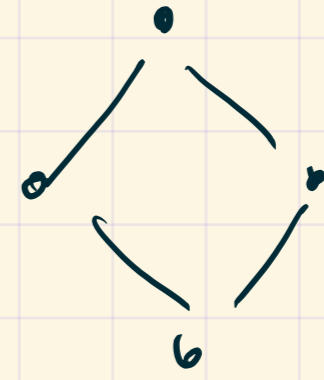
$$\begin{bmatrix} 1 & 0 & 1+c & 1-1+c+d \\ 0 & 1 & 0 & 1+0+g \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$c=-1, g=-1, d=1$$



The inverse of  $A$  is:

$$\begin{bmatrix} 1 & -1 & -1 & 1 \\ & 1 & 0 & -1 \\ & & 1 & -1 \\ & & & 1 \end{bmatrix} = A^{-1}$$



In fact, you can do this construction for any poset to produce the inverse for  $\zeta$ .

This inverse is called  $\mu$ , Möbius function of the poset  $(P, \leq)$ .

In fact,  $\mu$  has a recursive formula!  $\rightarrow$  Next time