

## MATH 2301

\* Mid-semester exam next week

\* Convolution reminders

\*\* If  $f, g \in A(P)$ , then  $f * g \in A(P)$

$$(f * g)([x,y]) = \sum_{z \geq x \geq y} f([x,z]) \cdot g([z,y])$$

### Remarks

In general,

- $(f * g)([x,y]) \neq f([x,y]) \cdot g([x,y])$
- $(f * g)([x,y]) \neq (g * f)([x,y])$  (not commutative)
- $((f * g) * h) = (f * (g * h))$  (it is associative)

### One-sided convolution

Let  $f \in A(P)$ ,  $p: P \rightarrow \mathbb{R}$ .

Then  $f * p$ ,  $p * f$  are functions  $P \rightarrow \mathbb{R}$ .

$$-(f * p)(x) = \sum_{z \geq x} f([x,z]) \cdot p(z)$$

$$-(p * f)(x) = \sum_{z \geq x} p(z) \cdot f([z,x])$$

\* Invertibility (with respect to  $*$ )

\*\* Def: An element  $f \in A(P)$  is said to be invertible if there exists  $g \in A(P)$ , such that  $f * g = \delta$

$$\left[ \delta([x,y]) = \begin{cases} 1 & \text{if } y=x \\ 0 & \text{otherwise} \end{cases} \right] \text{ or "Kronecker delta function"}$$

### Remarks

- (1) In that case, we say that  $g = f^{-1}$
- (2)  $\delta$  is its own inverse:  $\delta * \delta = \delta$
- (3) In this case, it is also true that  $g * f = \delta$ .

### Important example : $\zeta$

$$\begin{array}{c} 2 \bullet \\ \backslash \\ \bullet \\ / \\ 3 \end{array} \quad \text{Q: Is } \zeta \text{ invertible?}$$

$$\zeta([x,y]) = 1 + x \geq y$$

Let's try to find an inverse. Suppose an inverse exists. Call it  $\zeta^{-1}$ .

We need:

$$(\zeta * \zeta^{-1}) = \delta$$

This means:

inverse in  
the context  
of  $*$ ,  
not in the  
context of  
inverting  
functions.

$$(\zeta * \zeta^{\dagger})([x,y]) = \delta([x,y]) = \begin{cases} 1 & \text{if } y=x \\ 0 & \text{otherwise.} \end{cases}$$

i.e.

$$\sum_{\substack{x \leq z \leq y \\ z=1}} \zeta([x,z]) \cdot \zeta^{\dagger}([z,y]) = \delta([x,y])$$

$$\sum_{\substack{x \leq z \leq y \\ z=1}} \zeta^{\dagger}([z,y]) = \delta([x,y])$$

$\begin{array}{c} 2 \cdot \backslash / \cdot 3 \\ \vdots \end{array}$

Let's try a particular interval, say  $[2,2]$

i.e.  $x=2, y=2$

$$\zeta^{\dagger}([2,2]) = \delta([2,2]) = 1$$

$\Rightarrow \zeta^{\dagger}([2,2])$  must be equal to 1.

$\zeta^{\dagger}([1,1])$  and  $\zeta^{\dagger}([3,3])$  must also equal 1,  
by a similar calculation.

We still need  $\zeta^{\dagger}([1,2])$  &  $\zeta^{\dagger}([1,3])$

$x=1, y=2:$

$$\sum_{1 \leq z \leq 2} \zeta^{\dagger}([z,2]) = \delta([1,2])$$

i.e.  $\zeta^{\dagger}([1,2]) + \underbrace{\zeta^{\dagger}([2,2])}_{=1 \text{ by previous calculation}} = \delta([1,2]) = 0$

$\Rightarrow \zeta^{\dagger}([1,2]) = 0 - \zeta^{\dagger}([2,2]) = -1$

So  $\zeta^{\dagger}([1,2])$  must be  $-1$ .

Similarly, we can check that  $\zeta^{\dagger}([1,3]) = -1$

Now we have produced a candidate  $\zeta^{\dagger}$ :

$$\zeta^{\dagger}([a,a]) = 1 \quad \text{for any } a \in P$$

$$\zeta^{\dagger}([a,b]) = -1 \quad \text{for } a=1, b=2 \text{ or } 3$$

Technically, we should check that

$$(\zeta * \zeta^{\dagger}) = (\zeta^{\dagger} * \zeta) = \delta \text{ on any interval } [x,y]$$

But we've basically done this in the previous calculations

So for this poset, we have found an inverse!

\*\* Thm :  $\zeta$  is invertible for any finite poset.

The inverse  $\zeta^{\dagger}$  has a special name: mu  $\mu$

We'll come back to this theorem

\* Matrix representation of  $\Delta(P)$

Let  $P$  be a finite poset.

We'll now write elements of  $\Delta(P)$  as matrices.

Suppose  $f \in \Delta(P)$ ; we'll construct associated  $M_f$ .

① Choose any labelling of  $P$ :  $(P_1, P_2, \dots, P_n)$

(Any labelling is ok, but it's much better to choose a topological sorting)



② If  $P$  has  $n$  elements, make  $n \times n$  matrix.

$$i \rightarrow \left[ \begin{array}{c} \vdots \\ \bullet \end{array} \right] \quad j \downarrow$$

the  $(i,j)^{\text{th}}$  entry of  $M_f$   
is  $f([P_i; P_j])$  if  $P_i \leq P_j$   
is 0 otherwise

\*\* Example



$$\delta \in \Delta(P)$$

$$M_\delta = \begin{matrix} & 1 & 2 & 3 \\ 1 & 1 & 0 & 0 \\ 2 & 0 & 1 & 0 \\ 3 & 0 & 0 & 1 \end{matrix}$$

blue circled entries correspond to empty intervals

$$\zeta \in \Delta(P)$$

$$M_\zeta = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mu = \zeta^T \in \Delta(P)$$

$$M_\mu = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

from the calculation we did earlier.

\*\* Thm: Addition and convolution of elements of  $\Delta(P)$  correspond exactly to additions & matrix multiplications of the corresponding matrices.