

# MATH 2301

\* Mid-semester exam next week

\* Convolution reminders

\*\* If  $f, g \in A(P)$ , then  $f * g \in A(P)$

$$(f * g)([x, y]) = \sum_{x \leq z \leq y} f([x, z]) \cdot g([z, y])$$

## Rmks

In general,

$$- (f * g)([x, y]) \neq f([x, y]) \cdot g([x, y])$$

$$- (f * g)([x, y]) \neq (g * f)([x, y]) \quad (\text{not commutative})$$

$$- ((f * g) * h) = (f * (g * h)) \quad (\text{it is associative})$$

\*\* One-sided convolution

Let  $f \in A(P)$ ,  $P: P \rightarrow \mathbb{R}$ .

Then  $f * p$ ,  $p * f$  are functions  $P \rightarrow \mathbb{R}$ .

$$- (f * p)(x) = \sum_{x \leq z} f([x, z]) \cdot p(z)$$

$$- (p * f)(x) = \sum_{z \leq x} p(z) \cdot f([z, x])$$

## \* Invertibility (with respect to $*$ )

\*\* Def : An element  $f \in A(P)$  is said to be invertible if there exists  $g \in A(P)$ , such that  $f * g = \delta$

$$[\delta([x,y]) = \begin{cases} 1 & \text{if } y=x \\ 0 & \text{otherwise} \end{cases}] \text{ or "Kronecker delta function"}$$

### \*\* Remarks

(1) In that case, we say that  $g = f^{-1}$

(2)  $\delta$  is its own inverse:  $\delta * \delta = \delta$

(3) In this case, it is also true that  $g * f = \delta$ .

inverse in  
the context  
of  $*$ ,  
not in the  
context of  
inverting  
functions.

### \*\* Important example : $\zeta$ .

$$\begin{matrix} 2 & \bullet & & & 3 \\ & \backslash & / & & \\ & \bullet & & & \\ & & 1 & & \end{matrix}$$

Q: Is  $\zeta$  invertible?

$$\zeta([x,y]) = 1 + x^3 y$$

Let's try to find an inverse. Suppose an inverse exists. Call it  $\zeta^{-1}$ .

We need:

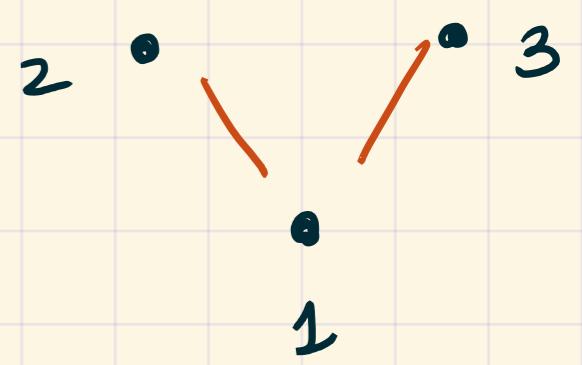
$$(\zeta * \zeta^{-1}) = \delta$$

This means:

$$(\zeta * \bar{\zeta})([x, y]) = \delta([x, y]) = \begin{cases} 1 & \text{if } y = x \\ 0 & \text{otherwise.} \end{cases}$$

i.e.  $\sum_{\substack{x \leq z \leq y \\ z \neq x}} \zeta([x, z]) \cdot \bar{\zeta}([z, y]) = \delta([x, y])$

$$\sum_{\substack{x \leq z \leq y \\ z \neq x}} \bar{\zeta}([z, y]) = \delta([x, y])$$



Let's try a particular interval, say  $[2, 2]$

i.e.  $x = 2, y = 2$

$$\bar{\zeta}([2, 2]) = \delta([2, 2]) = 1$$

$\Rightarrow \bar{\zeta}([2, 2])$  must be equal to 1.

$\bar{\zeta}([1, 1])$  and  $\bar{\zeta}([3, 3])$  must also equal 1,

by a similar calculation.

We still need  $\bar{\zeta}([1, 2])$  &  $\bar{\zeta}([1, 3])$

$x = 1, y = 2$ :

$$\sum_{1 \leq z \leq 2} \bar{\zeta}([z, 2]) = \delta([1, 2])$$

i.e.  $\bar{\zeta}([1, 2]) + \underbrace{\bar{\zeta}([2, 2])}_{= 1 \text{ by previous calculation}} = \delta([1, 2]) = 0$

$\Rightarrow \bar{\zeta}([1, 2]) = 0 - \bar{\zeta}([2, 2]) = -1$

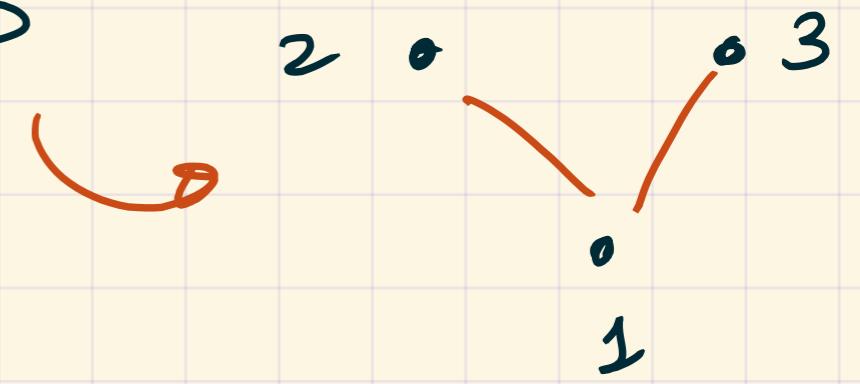
So  $\bar{\zeta}([1, 2])$  must be  $-1$ .

Similarly, we can check that  $\zeta'([1, 3]) = -1$

Now we have produced a candidate  $\zeta'$ :

$$\zeta'([a, a]) = 1 \quad \text{for any } a \in P$$

$$\zeta'([a, b]) = -1 \quad \begin{aligned} &\text{for } a=1, \\ &b=2 \text{ or } 3. \end{aligned}$$



Technically, we should check that

$$\underline{(\zeta * \zeta')} = (\zeta' * \zeta) = \delta \text{ on any interval } [x, y].$$

But we've basically done this in the previous calculations

So for this poset, we have found an inverse!

Thm:  $\zeta$  is invertible for any finite poset.

The inverse  $\zeta'$  has a special name: mu  $\mu$

We'll come back to this theorem

## \* Matrix representation of $\Delta(P)$

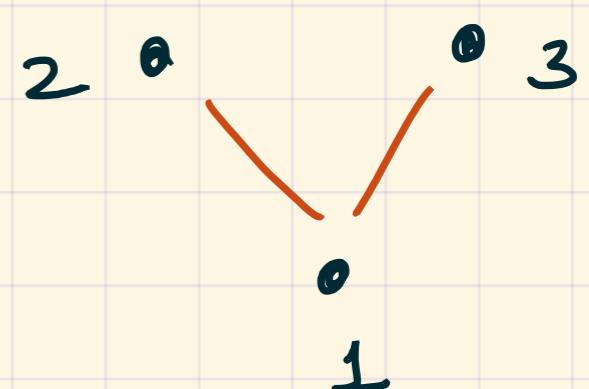
Let  $P$  be a finite poset.

We'll now write elements of  $\Delta(P)$  as matrices.

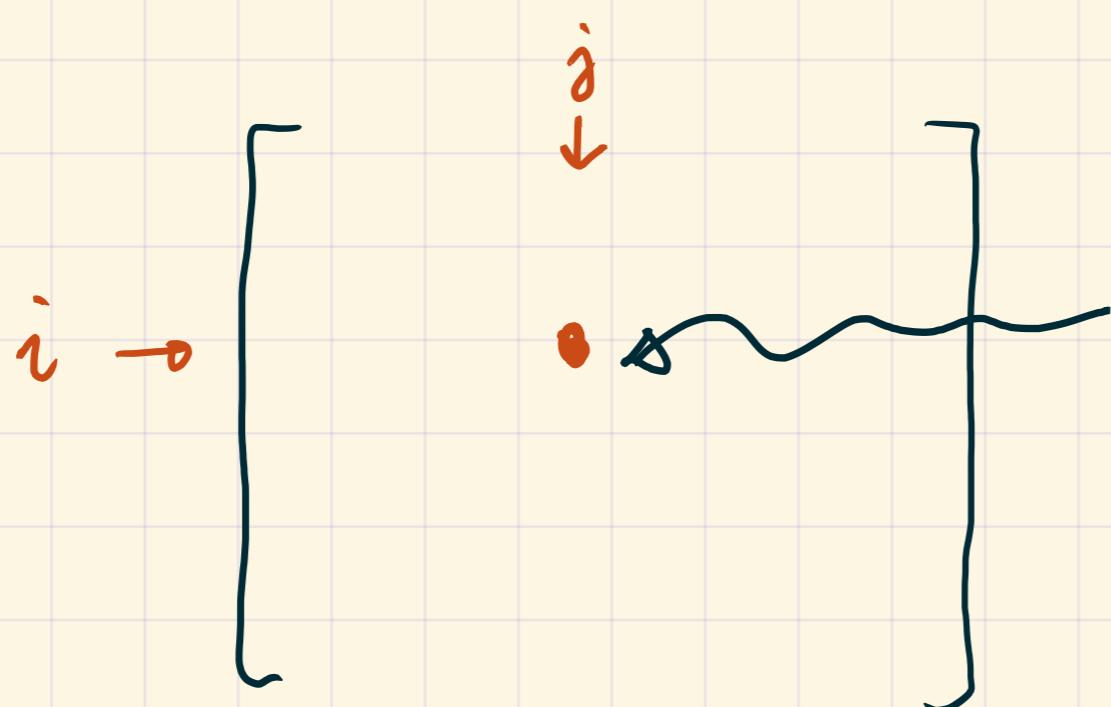
Suppose  $f \in \Delta(P)$ ; we'll construct associated  $M_f$ .

① Choose any labelling of  $P$ :  $(P_1, P_2, \dots, P_n)$

(Any labelling is ok, but it's much better to choose a topological sorting)

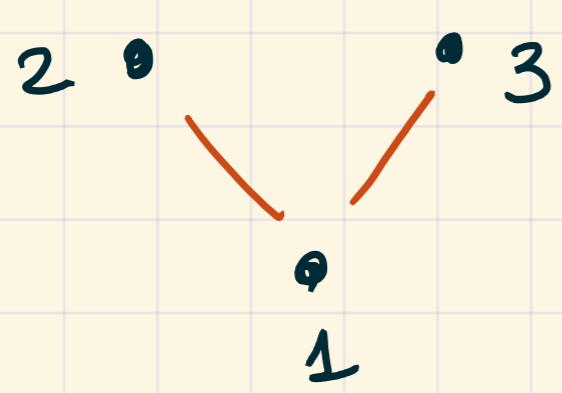


② If  $P$  has  $n$  elements, make  $n \times n$  matrix.



the  $(i, j)^{\text{th}}$  entry of  $M_f$   
is  $f([P_i, P_j])$  if  $P_i \leq P_j$   
is 0 otherwise

### Example



$\delta \in \Delta(P)$

$$M_\delta = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

blue circled entries correspond  
to empty intervals

$\zeta \in \Delta(P)$

$$M_\zeta = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mu = \vec{z}^T \in \mathcal{A}(P)$$

$$M_\mu = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

from the  
calculation  
we did  
earlier.

Thm: Addition and convolution of elements of  $\mathcal{A}(P)$  correspond exactly to additions & matrix multiplications of the corresponding matrices.